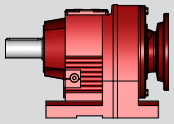
R-045



Ratio	Stages	n_{1N} (1)	n_{1Max} (2)	T_{2N} (3)	T_{2Max} (4)	T_{2E} (5)	F_{RMax}	J (6)	C	Δφ	η	M
		rpm	rpm	N·m	N·m	N·m	N	Kg·cm²	N·m/'	'	%	Kg
3.83	2	1400	3657	144	166	245	2080	2.6	11	11	97	15-29.15
4.34	2	1400	4144	146	170	245	2190	2.0	11	11	97	15-29.15
4.85	2	1400	4500	150	175	255	2280	1.7	11	10	97	15-29.15
5.64	2	1400	4500	155	180	260	2410	1.3	11	10	97	15-29.15
6.00	2	1400	4500	156	182	265	2470	1.2	11	10	97	15-29.15
6.96	2	1400	4500	159	187	270	2620	0.93	11	10	97	15-29.15
7.76	2	1400	4500	163	190	275	2720	0.77	11	10	97	15-29.15
8.01	2	1400	4500	205	300	345	2690	2.0	15	8	97	15-29.15
9.07	2	1400	4500	220	305	370	2780	1.6	15	8	97	15-29.15
10.15	2	1400	4500	230	305	390	2880	1.3	15	7	97	15-29.15
11.79	2	1400	4500	245	305	415	3020	1.1	15	7	97	15-29.15
12.54	2	1400	4500	250	305	425	3080	0.95	15	7	97	15-29.15
14.56	2	1400	4500	265	305	450	3230	0.74	15	7	97	15-29.15
16.22	2	1400	4500	275	305	465	3350	0.63	15	7	97	15-29.15
17.89	2	1400	4500	290	305	490	3390	0.51	15	7	97	15-29.15
19.27	2	1400	4500	295	305	500	3530	0.48	15	7	97	15-29.15
21.81	2	1400	4500	300	305	510	3710	0.39	15	7	97	15-29.15
23.28	2	1400	4500	300	305	510	3820	0.36	15	7	97	15-29.15
26.74	2	1400	4500	300	305	510	4050	0.29	15	7	97	15-29.15
31.12	2	1400	4500	220	305	370	4610	0.23	15	7	97	15-29.15
33.79	2	1400	4500	240	305	405	4680	0.20	15	7	97	15-29.15
23.59	3	1400	4500	300	305	510	3840	1.7	15	8	95	16-29.15
26.70	3	1400	4500	300	305	510	4050	1.4	15	8	95	16-29.15
29.88	3	1400	4500	300	305	510	4240	1.2	15	8	95	16-29.15
34.73	3	1400	4500	300	305	510	4520	0.93	15	8	95	16-29.15
36.93	3	1400	4500	300	305	510	4630	0.85	15	8	95	16-29.15
42.87	3	1400	4500	300	305	510	4930	0.67	15	8	95	16-29.15
47.75	3	1400	4500	300	305	510	5140	0.56	15	8	95	16-29.15
52.69	3	1400	4500	300	305	510	5350	0.47	15	8	95	16-29.15
56.73	3	1400	4500	300	305	510	5420	0.44	15	8	95	16-29.15
64.21	3	1400	4500	300	305	510	5420	0.37	15	8	95	16-29.15
68.54	3	1400	4500	300	305	510	5420	0.33	15	8	95	16-29.15

(1) Rated input speed.

(2) Maximum Input Speed.

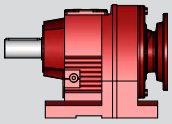
(3) T2N value is calculated at n1n, continuous duty cycle, uniform operation, KA=1 and unlimited theoretical life time as per ISO-6336 (NL>N00 in the Woehler line). The application factor KA according to DIN-3990-1 must be considered for each duty cycle and machine type.

(4) T2Max only for very short time intervals.

(5) Up to 1000 times during the gearbox's lifetime.

(6) Varies depending on input.

R-045



Ratio	Stages	n_{1N} (1)	n_{1Max} (2)	T_{2N} (3)	T_{2Max} (4)	T_{2E} (5)	F_{RMax}	J (6)	C	Δφ	η	M
		rpm	rpm	N·m	N·m	N·m	N	Kg·cm²	N·m/'	'	%	Kg
76.23	3	1400	4500	300	305	510	5420	0.60	15	7	94	16-29.15
84.90	3	1400	4500	300	305	510	5420	0.52	15	7	94	16-29.15
93.68	3	1400	4500	300	305	510	5420	0.43	15	7	94	16-29.15
100.86	3	1400	4500	300	305	510	5420	0.41	15	7	93	16-29.15
114.17	3	1400	4500	300	305	510	5420	0.34	15	7	93	16-29.15
121.87	3	1400	4500	300	305	510	5420	0.31	15	7	93	16-29.15
139.99	3	1400	4500	300	305	510	5420	0.25	15	7	93	16-29.15
162.94	3	1400	4500	300	305	510	5420	0.20	15	7	93	16-29.15
176.88	3	1400	4500	300	305	510	5420	0.18	15	7	93	16-29.15

(1) Rated input speed.

(2) Maximum Input Speed.

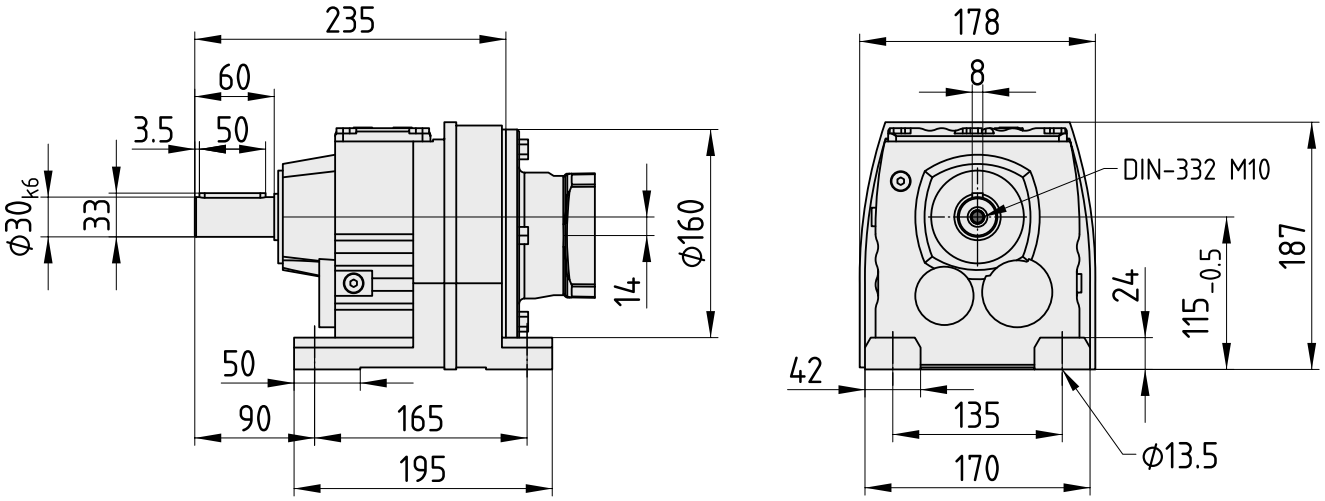
(3) T2N value is calculated at n1n, continuous duty cycle, uniform operation, KA=1 and unlimited theoretical life time as per ISO-6336 (NL>N00 in the Woehler line). The application factor KA according to DIN-3990-1 must be considered for each duty cycle and machine type.

(4) T2Max only for very short time intervals.

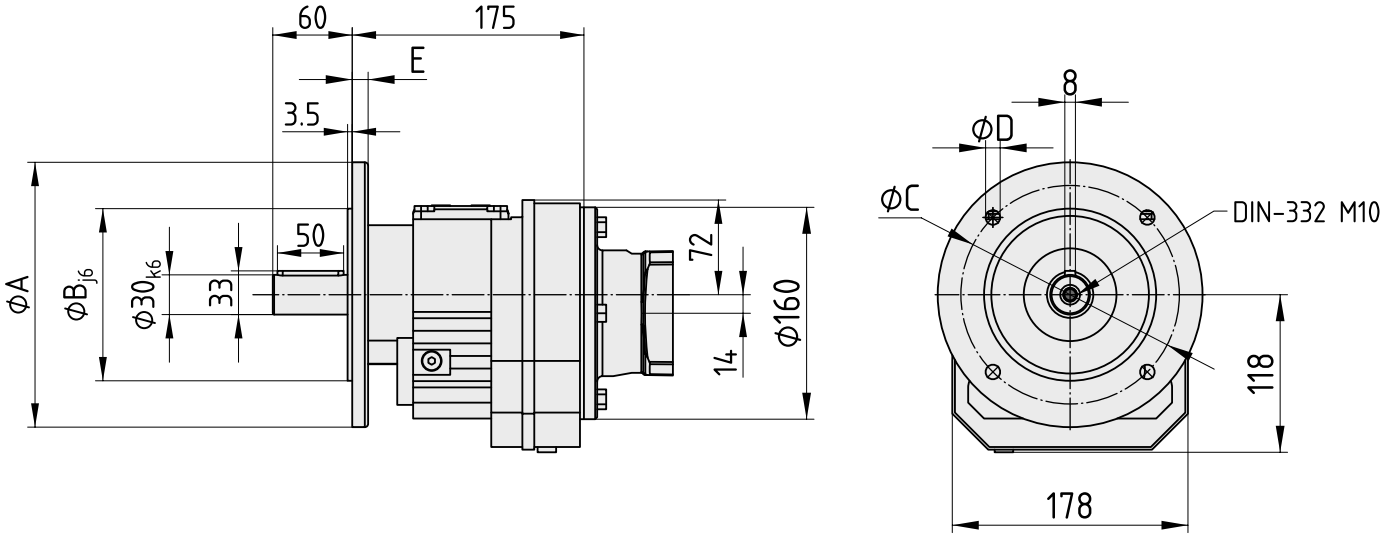
(5) Up to 1000 times during the gearbox's lifetime.

(6) Varies depending on input.

RG-045: Foot Mounted



RF□-Flange Mounted

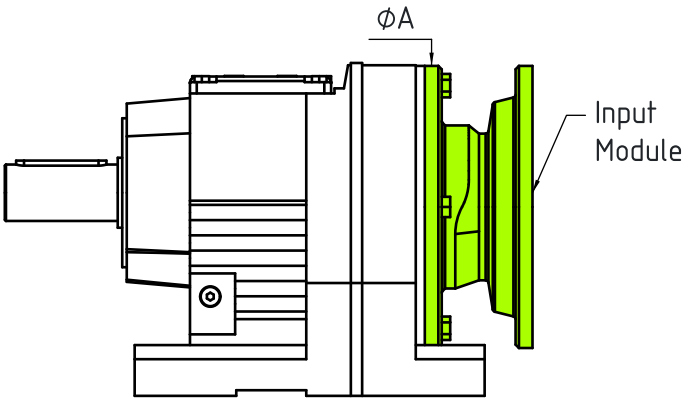


Flange	A	B	C	D	E
RF1-045	140	95	115	9	10
RF2-045	160	110	130	9	10
RF3-045	200	130	165	11	12

Input Modules

To simplify input module selection, Servotak uses modular input blocks. Each gearbox size and family combination has a interface code, that lets you quickly determine which input modules can be installed. Input modules are shared between R, F and K gearboxes. A is the diameter of the interface flange for that gearbox.

Input Module



Reference	Interface Code	A
R□-015	A	105
R□-025	B	120
R□-035	B	120
R□-045	C	160
R□-055	C	160
R□-065	C	160
R□-075	D	200
R□-085	E	250
R□-095	F	300
R□-105	G	350
R□-135	H	400
R□-145	I	450
R□-165	J	550

Reference	Interface Code	A
F□-035	B	120
F□-045	B	120
F□-055	C	160
F□-065	C	160
F□-075	D	200
F□-085	E	250
F□-095	F	300
F□-105	G	350
F□-125	I	450
F□-155	J	550

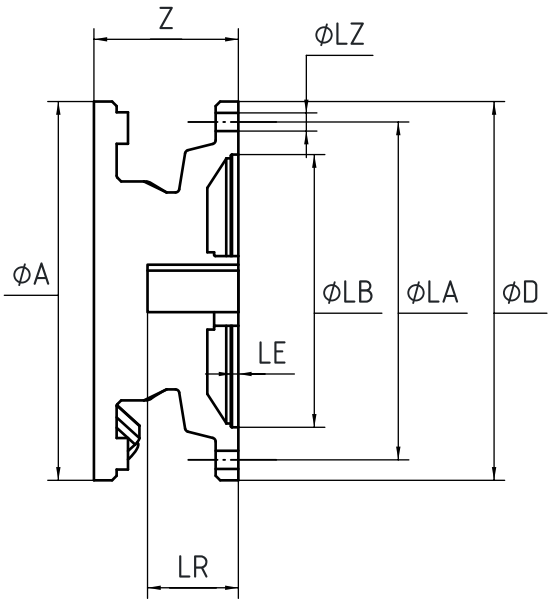
Reference	Interface Code	A
K□-035	B	120
K□-045	C	160
K□-055	C	160
K□-065	C	160
K□-075	D	200
K□-085	E	250
K□-095	F	300
K□-105	G	350
K□-125	I	450
K□-155	J	550
K□-165	J	550
K□-185	J	550

IEC Motor Flanges

Each standard IEC motor flange has a set number of interfaces with which it is compatible. Z5 is the length of the input flange, and sometimes varies between interfaces. All IEC motor flanges are for IM B5 / IM V1 / IM V3 Motors.

Motor Size	Interface Code	Z
63	A, B, C	50
63	D	54
71	A, B, C, D	54
80	A, B, C, D, E	69
90	B, C, D, E	69
100	C, D, E, F, G	81
112	C, D, E, F, G	81
132	D, E, F, G, H, I	92

Motor Size	Interface Code	Z
160	E, F	125
160	G, H, I, J	124
180	E, F	125
180	G, H, I, J	124
200	F, G, H, I, J	144
225	F, G, H, I, J	159
250	I, J	180
280	I, J	180



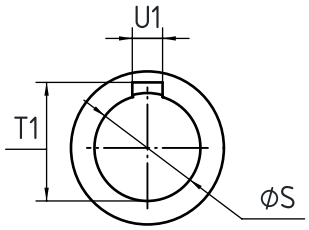


Fig. 1

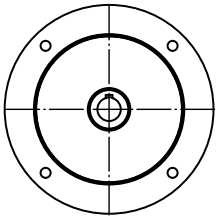
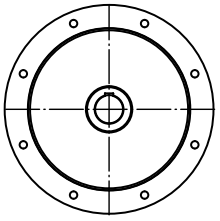


Fig. 2

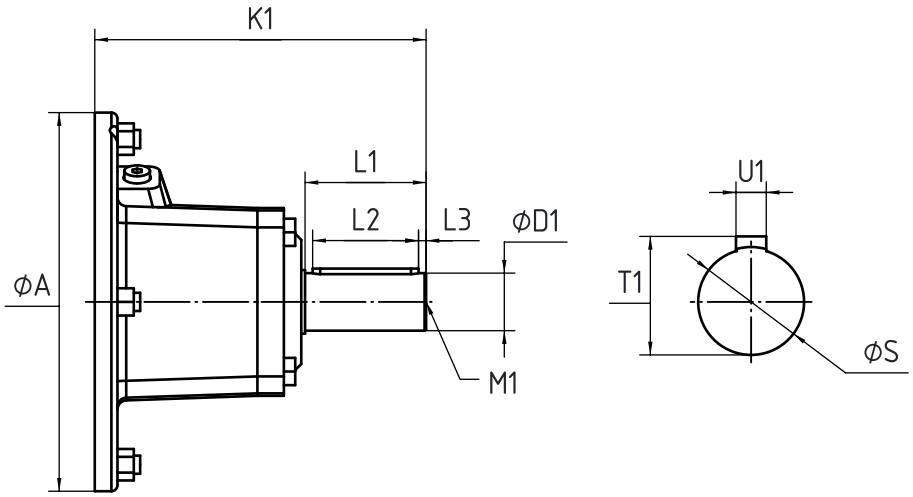


Motor Size	LB	LA	LE	D	LZ	S	LR	T1	U1	Fig
63	95	115	3.5	140	M08	11	23	12.8	4	1
71	110	130	3.5	160	M08	14	30	16.3	5	1
80	130	165	4.5	200	M10	19	40	21.8	6	1
90	130	165	4.5	200	M10	24	50	27.3	8	1
100	180	215	5	250	M12	28	60	31.3	8	1
112	180	215	5	250	M12	28	60	31.3	8	1
132	230	265	5	300	M12	38	80	41.3	10	1
160	250	300	6	350	M16	42	110	45.3	12	1
180	250	300	6	350	M16	48	110	51.8	14	1
200	300	350	7	400	M16	55	110	59.3	16	1
225	350	400	7	450	M16	60	140	64.4	18	2
250	450	500	7	550	M16	65	140	69.4	18	2
280	450	500	7	550	M16	75	140	79.9	20	2

Solid Input Shafts

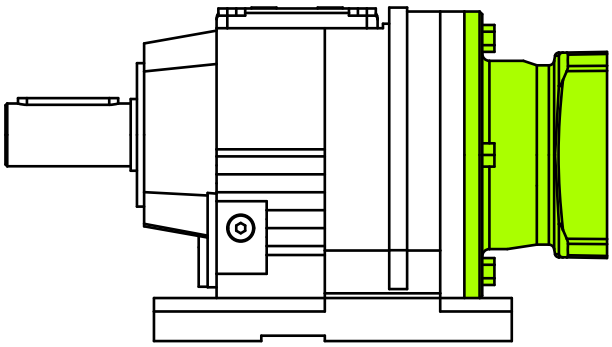
Each solid input shaft has a set of interfaces with which it is compatible. K1 is the length from the interface to the tip of the shaft.

Shaft Size	Interface Code	K1
E14×30	A	72
E16×40	B	102
E19×40	B	130
E19×40	C	123
E19×40	D	116
E19×40	E	111
E24×50	C	159
E24×50	D	151
E28×60	E	156
E28×60	F	151
E28×60	G	145
E38×80	D	224
E38×80	E	219
E38×80	F	214
E38×80	G	208
E38×80	H	201
E38×80	I	193
E42×110	E	292
E42×110	F	287
E42×110	G	281
E42×110	H	274
E42×110	I	266
E42×110	J	258
E48×110	F	327
E48×110	G	321
E48×110	H	314
E48×110	I	306
E48×110	J	298
E55×110	H	308
E55×110	I	300
E55×110	J	292
E70×140	I	383
E70×140	J	374



Shaft Size	D1	L1	L13	L14	T1	U1	M
E14×30	14	30	4	22	16	5	M05
E16×40	16	40	4	32	18	5	M05
E19×40	19	40	4	32	21.5	6	M06
E24×50	24	50	5	40	27	8	M08
E28×60	28	60	5	50	31	8	M10
E38×80	38	80	5	70	41	10	M12
E42×110	42	110	10	70	45	12	M16
E48×110	48	110	10	80	51.5	14	M16
E55×110	55	110	10	90	59	16	M20
E70×140	70	140	15	110	74.5	20	M20

Servomotor Flanges



Since servomotors, unlike IEC motors, don’t have standard dimensions, it is necessary to know the exact dimensions of the servomotor to ascertain the correct input flange for it. Input flanges are often custom made for the customer’s order, which allows Servotak to provide flanges for basically every servomotor. The structure of the reference for the servomotor input flange is detailed at the end of this document, Order References chapter.